

**Amendments to the Claims**

Claims 1 – 61 (cancelled).

62. (previously presented) A wide field of view scanner, comprising:  
a scanning assembly constructed to provide a light excitation beam emitted from  
a light source in a scanning motion to an examined surface;  
an objective lens associated with and displaced by said scanning assembly  
arranged to provide an optical path from said light source to the examined surface and  
from the examined surface [fluorescent light, excited in response to said excitation  
beam] to a light detector; [said displaced objective lens and said scanning assembly  
providing said optical path having substantially constant length;]  
a translation system constructed to produce movement of the examined surface;  
and  
a data collection control and processing unit arranged to collect data during the  
scanning motion and process the collected data.

63. (previously presented) The scanner of claim 62 wherein said scanning  
assembly includes oscillating support structure comprising a scan arm constructed to  
support said objective lens.

64. (previously presented) The scanner of claim 63 wherein said support  
structure includes a periscope assembly arranged to provide said optical path including  
said objective lens.

65. (previously presented) The scanner of claim 62 further comprising focusing  
system including a tilting mechanism constructed to tilt said examined surface for  
focusing light passing through said objective lens.

66. (previously presented) The scanner of claim 62 wherein said data collection  
control and processing unit is constructed to collect optical data over an arcuate scan

motion of said objective lens and arranged to time the data collection during the arcuate scan motion.

67. (previously presented) The scanner of claim 66 including a data conversion system arranged to convert said collected data to a raster grid by averaging, for each raster point, the value of data points near the raster point, the values being weighted by their respective distances from the raster point.

68. (previously presented) The scanner of claim 62 wherein said objective lens has a numerical aperture larger than 0.5.

69. (previously presented) The scanner of claim 62 wherein said surface is part of a microscope slide comprising said biological material.

70. (previously presented) The scanner of claim 62 wherein said surface is part of a DNA chip arranged for hybridization of a biological material prior to scanning.

71. (previously presented) The scanner of claim 62 wherein said surface is part of a DNA chip comprising said biological material arranged for DNA sequencing.

72. (previously presented) A wide field of view scanner, comprising:  
a scanning assembly including an oscillating support structure constructed to support and displace a micro-objective lens in a scanning motion, said oscillating support structure providing a constant optical path;  
a driver constructed to displace said support structure in an oscillating motion;  
a position transducer associated with said scanning assembly and constructed to provide a position signal corresponding to a position of said micro-objective lens during said scanning motion;  
a light source constructed to emit excitation light directed to an object including biological material;

a optical detector constructed to detect fluorescent light excited in response to said excitation light from said object;

a translation system constructed to produce movement of the object; and

a data collection control and processing unit constructed and arranged to receive position signal from said position transducer and optical data from said optical detector.

73. (previously presented) The scanner of claim 72 wherein said micro-objective lens is an aspheric lens.

74. (previously presented) The scanner of claim 72 arranged for confocal detection of said fluorescent light.

75. (previously presented) The scanner of claim 72 wherein said scanning assembly includes a periscope assembly arranged to provide said optical path including said micro-objective lens.

76. (previously presented) The scanner of claim 75 wherein said micro-objective lens receives said fluorescent light stimulated by a spot of said excitation light passing through said micro-objective lens.

77. (currently amended) The scanner of claim 72 wherein said processing unit is constructed to generate an image from said detected fluorescent light.

78. (previously presented) The scanner of claim 72 wherein said driver and said translation system are constructed and arranged to scan said object in form of a microscope slide.

79. (previously presented) The scanner of claim 72 wherein said driver and said translation system are constructed and arranged to scan said object in form of a DNA chip.

80. (previously presented) The scanner of claim 72 wherein said driver and said translation system are constructed and arranged to scan said object in form of a hybridization array.

81. (previously presented) The scanner of claim 72 including an optical merging system constructed to merge at least two light beams into a single beam directed over said optical path extending over said support structure to said micro-objective lens.

82. (previously presented) A wide field of view scanner, comprising:  
a scanning assembly including an oscillating support structure constructed to support and displace a micro-objective lens in a scanning motion;  
a driver constructed to displace said support structure in an oscillating motion;  
a position transducer associated with said scanning assembly and constructed to provide a position signal corresponding to a position of said micro-objective lens during said scanning motion;  
a light source constructed to emit excitation light directed to an object including biological material;  
a optical detector constructed to detect fluorescent light excited in response to said excitation light from said object; and  
a data collection control and processing unit constructed and arranged to receive said position signal from said position transducer and optical data from said optical detector, said data collection control and processing unit providing a set of discrete position data each representing a position of said micro-objective lens, and generating a plurality of sample times based, at least in part, on a comparison of the position signal with the position data; and directing sampling said fluorescent light when enabled by the plurality of said sample times.

83. (previously presented) The scanner of claim 82 wherein said scanning assembly includes a rigid periscope assembly arranged to provide said optical path including said micro-objective lens.

84. (previously presented) The scanner of claim 83 wherein said micro-objective lens receives said fluorescent light stimulated by a spot of said excitation light passing through said micro-objective lens.

85. (currently amended) The scanner of claim 82 wherein said processing unit is constructed to generate an image from said detected fluorescent light.

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d*  
86. (previously presented) The scanner of claim 82 including a translation system constructed to produce movement of the object.

*l  
r*  
87. (previously presented) The scanner of claim 86 wherein said driver and said translation system are constructed and arranged to scan said object in form of a microscope slide.

88. (previously presented) The scanner of claim 86 wherein said driver and said translation system are constructed and arranged to scan said object in form of a DNA chip.

89. (previously presented) The scanner of claim 86 wherein said driver and said translation system are constructed and arranged to scan said object in form of a hybridization array.

90. (new) The scanner of claim 72 wherein said data control and processing unit is constructed to provide a set of discrete position data, and constructed to generate a plurality of sample times based, at least in part, on a comparison of the position signal with the position data; and to direct sampling said fluorescent light when enabled by the plurality of said sample times.